

Derivations of Navier-Stokes Continuity and Momentum Equations From Reynolds Transport Theorem

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1 Reynolds Transport Theorem

To elucidate the concept of the Reynolds Transport Theorem (RTT), we consider a control volume (CV) initially filled with a quantity B that flows at a fixed speed \mathbf{u} . After some time, portions of B initially inside the volume move outside and new portions of B enter, as depicted by [Figure 1](#).

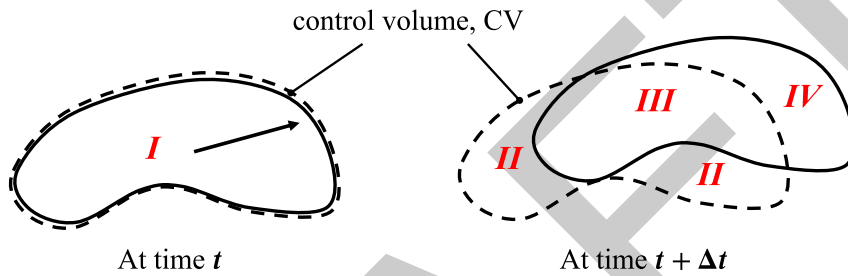


Figure 1: Movement of a physical quantity B by fluid flow from inside to outside of the control volume.

Regions in [Figure 1](#) are

- **I**: the entire fluid system within CV at time t
- **II**: new fluid that has entered CV at time $t + \Delta t$
- **III**: portion of fluid system that remains inside CV at time $t + \Delta t$
- **IV**: portion of a fluid system that is outside of CV at time $t + \Delta t$

By conservation of the quantity B in the CV, "how much out must be balanced by how much in",

$$\begin{aligned}
 \underbrace{B_{\text{system}}|_{t+\Delta t} - B_{\text{system}}|_t}_{\text{change of } B \text{ in system}} &= B_{III} + B_{IV} - B_I \\
 &= \underbrace{(B_{III} + B_{II} - B_I)}_{\text{change of } B \text{ in CV}} + \underbrace{(B_{IV} - B_{II})}_{\text{Net amount of } B \text{ leaving CV due to flow}} \\
 \underbrace{B_{\text{system}}|_{t+\Delta t} - B_{\text{system}}|_t}_{\text{Term A}} &= \underbrace{B_{CV}|_{t+\Delta t} - B_{CV}|_t}_{\text{Term B}} \\
 &\quad + \underbrace{\text{Net amount of } B \text{ leaving CV due to flow}}_{\text{Term C}}
 \end{aligned}$$

Divide each term by Δt , and limit the change in time to infinitesimally small: $\Delta t \rightarrow 0$.

Term A: rate of change of B within the system (Lagrangian description)

$$\lim_{\Delta t \rightarrow 0} \frac{B_{\text{system}}|_{t+\Delta t} - B_{\text{system}}|_t}{\Delta t} = \frac{dB_{\text{system}}}{dt}.$$

Term B: rate of change of B within CV (Eulerian description)

$$\lim_{\Delta t \rightarrow 0} \frac{B_{CV}|_{t+\Delta t} - B_{CV}|_t}{\Delta t} = \frac{\partial B_{CV}}{\partial t} = \frac{\partial}{\partial t} \int_{CV} \rho \beta \, dV,$$

where $\beta = \frac{dB}{dm}$ is the amount of B per unit mass.

Term C: rate of change of B within CV as it is lost by fluid flow (Eulerian description)

$$\begin{aligned} \lim_{\Delta t \rightarrow 0} \frac{\text{Net amount of } B \text{ leaving CV due to flow}}{\Delta t} &= \text{rate of } B \text{ leaving CV due to flow} \\ &= \oint_{CS} \rho \beta (\mathbf{u} \cdot \hat{\mathbf{n}}) \, dA, \end{aligned}$$

where $(\mathbf{u} \cdot \hat{\mathbf{n}})$ quantifies the velocity component in the direction of the normal vector $\hat{\mathbf{n}}$.

By equating **Term A = Term B + Term C**,

$$\boxed{\frac{dB_{\text{system}}}{dt} = \frac{\partial}{\partial t} \int_{CV} \rho \beta \, dV + \oint_{CS} \rho \beta (\mathbf{u} \cdot \hat{\mathbf{n}}) \, dA}, \quad (1.1)$$

which is the final expression of RTT.

In other words, $\left(\begin{array}{c} \text{Rate of change of} \\ B \text{ in the system} \end{array} \right) = \left(\begin{array}{c} \text{Rate of change of} \\ B \text{ in control volume} \end{array} \right) + \left(\begin{array}{c} \text{Net flux of } B \text{ out of} \\ \text{control volume} \end{array} \right).$

2 Conservation of Mass

For the following derivations, an infinitesimally small cube positioned in the Cartesian coordinate system is selected as the CV. The length of the edges is δ , hence, the coordinates of the two diagonal nodes are (x_0, y_0, z_0) and $(x_0 + \delta, y_0 + \delta, z_0 + \delta)$, respectively. A surface on the cube has an area $A = \delta^2$, the cube has a volume $V = \delta^3$.

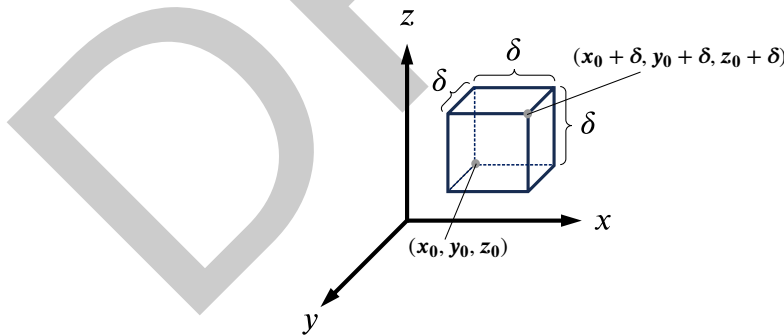


Figure 2: Control volume used for the analysis.

Expressed in the language of RTT, mass conservation simply means the overall rate of change of mass is 0. Here, the physical quantity ' B ' is mass, m ; hence, following the definition, $\beta = \frac{dB}{dm} = \frac{dm}{dm} = 1$. Mathematically,

$$0 = \frac{\partial}{\partial t} \int_{CV} \rho \, dV + \oint_{CS} \rho (\mathbf{u} \cdot \hat{\mathbf{n}}) \, dA. \quad (2.1)$$

To evaluate the first integral in Equation 2.1, assume the variation of the density ρ is negligible within the CV, hence, $\int_{CV} \rho dV \approx \rho V = \rho \delta^3$. Differentiate the integral w.r.t. the time t ,

$$\frac{\partial}{\partial t} \int_{CV} \rho dV \approx \frac{\partial(\rho \delta^3)}{\partial t} = \delta^3 \frac{\partial \rho}{\partial t}. \quad (2.2)$$

To evaluate the second integral in Equation 2.1, we need to count the flow passing through the surfaces in three orthogonal directions. For the x -direction, the velocity component is u_x , the inlet and outlet surfaces are positioned at $x = x_0$ and $x = x_0 + \delta$, respectively; therefore,

$$\oint_{CS} \rho u_x dA = (\rho u_x \delta^2) \Big|_{x=x_0}^{x=x_0+\delta} = \delta^3 \left(\frac{(\rho u_x)|_{x=x_0+\delta} - (\rho u_x)|_{x=x_0}}{\delta} \right) \approx \delta^3 \frac{\partial(\rho u_x)}{\partial x}. \quad (2.3)$$

Similarly, for flow in the y -direction and z -direction, the surface integrals are

$$\oint_{CS} \rho u_y dA \approx \delta^3 \frac{\partial(\rho u_y)}{\partial y}, \quad (2.4)$$

$$\oint_{CS} \rho u_z dA \approx \delta^3 \frac{\partial(\rho u_z)}{\partial z}. \quad (2.5)$$

Combine Equation 2.3, 2.4, 2.5,

$$\oint_{CS} \rho (\mathbf{u} \cdot \hat{\mathbf{n}}) dA = \delta^3 \left(\frac{\partial(\rho u_x)}{\partial x} + \frac{\partial(\rho u_y)}{\partial y} + \frac{\partial(\rho u_z)}{\partial z} \right), \quad (2.6)$$

or, in compact notation,

$$\oint_{CS} \rho (\mathbf{u} \cdot \hat{\mathbf{n}}) dA = \delta^3 \nabla \cdot (\rho \mathbf{u}).$$

Substituting Equation 2.2 and Equation 2.6 into Equation 2.1 yielding the celebrated continuity equation

$$0 \approx \delta^3 \frac{\partial \rho}{\partial t} + \delta^3 \nabla \cdot (\rho \mathbf{u}) \Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0}. \quad (2.7)$$

For incompressible fluid flow, the density ρ is constant, *i.e.*, it is invariant of time and space. This allows us to separate such a term from any partial derivatives in the equation, yielding the form

$$\nabla \cdot \mathbf{u} = 0. \quad (2.8)$$

3 Conservation of Linear Momentum

The linear momentum is the product between the mass and the velocity, $\mathbf{P} = m\mathbf{u}$. Hence, $\beta = \frac{d\mathbf{P}}{dm} = \mathbf{u}$. By RTT, the conservation of linear momentum is

$$\mathbf{F} = \frac{\partial}{\partial t} \int_{CV} \rho \mathbf{u} dV + \oint_{CS} \rho \mathbf{u} (\mathbf{u} \cdot \hat{\mathbf{n}}) dA. \quad (3.1)$$

The L.H.S. of Equation 3.1 is the total force exerted on the same CV as shown in Figure 2. The total force can be further decomposed into

- The internal force that acts on the surfaces of the CV. It is comprised of the hydrostatic force that raises from the pressure load from the fluid flow; and the deviatoric force which is due to the fluid shear as the fluid moves with a velocity.

$$\mathbf{F}_{\text{internal}} = \underbrace{-V \nabla p}_{\text{hydrostatic}} + \underbrace{V \mu \nabla^2 \mathbf{u}}_{\text{deviatoric}}.$$

(Note that the “force” we mentioned here is force **per unit volume** [N/m³] - hence, we multiply the volume to recover the actual force of the unit Newton.)

- The external force acting on CV that may be due to the presence of gravity, electromagnetism, etc.

$$\mathbf{F}_{\text{external}} = m\mathbf{f} = \rho V \mathbf{f}.$$

Hence, the total force

$$\mathbf{F} = \mathbf{F}_{\text{internal}} + \mathbf{F}_{\text{external}} = V(-\nabla p + \mu \nabla^2 \mathbf{u} + \rho \mathbf{f}). \quad (3.2)$$

You may recognise the expression enclosed in the bracelet in Equation 3.2 is the R.H.S. of the Navier-Stokes (N-S) momentum equation.

The first integral on the R.H.S. of Equation 3.1 is evaluated following the same fashion as demonstrated in the derivation of mass conservation. Assume change of ρ and \mathbf{u} is negligible within the CV, $\int_{CV} \rho \mathbf{u} dV \approx \rho \mathbf{u} V = \delta^3 \rho \mathbf{u}$, hence

$$\frac{\partial}{\partial t} \int_{CV} \rho \mathbf{u} dV \approx \frac{\partial(\delta^3 \rho \mathbf{u})}{\partial t} = \delta^3 \frac{\partial(\rho \mathbf{u})}{\partial t}. \quad (3.3)$$

The second integral on the R.H.S. of Equation 3.1, we first consider the flow passing through the surfaces at the x -direction only, i.e., $\mathbf{u} \cdot \hat{\mathbf{n}} = u_x$, leading to

$$\oint_{CS} \rho \mathbf{u} u_x dA = \rho \mathbf{u} u_x \delta^2 \Big|_{x=x_0}^{x=x_0+\delta} = \delta^3 \left(\frac{\rho \mathbf{u} u_x|_{x=x_0+\delta} - \rho \mathbf{u} u_x|_{x=x_0}}{\delta} \right) \approx \delta^3 \frac{\partial(\rho \mathbf{u} u_x)}{\partial x}. \quad (3.4)$$

Similarly, for flow in the y -direction and z -direction, the surface integrals are

$$\oint_{CS} \rho \mathbf{u} u_y dA \approx \delta^3 \frac{\partial(\rho \mathbf{u} u_y)}{\partial y}, \quad (3.5)$$

$$\oint_{CS} \rho \mathbf{u} u_z dA \approx \delta^3 \frac{\partial(\rho \mathbf{u} u_z)}{\partial z}. \quad (3.6)$$

Combine Equation 3.4, 3.5, 3.6,

$$\oint_{CS} \rho \mathbf{u} (\mathbf{u} \cdot \hat{\mathbf{n}}) dA \approx \delta^3 \left(\frac{\partial(\rho \mathbf{u} u_x)}{\partial x} + \frac{\partial(\rho \mathbf{u} u_y)}{\partial y} + \frac{\partial(\rho \mathbf{u} u_z)}{\partial z} \right). \quad (3.7)$$

Substituting Equation 3.2, Equation 3.7, and Equation 3.3 into Equation 3.1, neglecting the common term $V = \delta^3$ from both sides, yielding the expression of the N-S momentum equation

$$\frac{\partial(\rho \mathbf{u})}{\partial t} + \frac{\partial(\rho \mathbf{u} u_x)}{\partial x} + \frac{\partial(\rho \mathbf{u} u_y)}{\partial y} + \frac{\partial(\rho \mathbf{u} u_z)}{\partial z} = -\nabla p + \mu \nabla^2 \mathbf{u} + \rho \mathbf{f}. \quad (3.8)$$

One final step to take is rearranging the unsteady and convective acceleration terms on the L.H.S. of Equation 3.8. We can assume the fluid is incompressible, allowing us to separate ρ from the partial derivatives. Therefore,

$$\begin{aligned} \frac{\partial(\rho \mathbf{u})}{\partial t} &= \rho \frac{\partial \mathbf{u}}{\partial t}, \\ \frac{\partial(\rho \mathbf{u} u_x)}{\partial x} &= \rho \frac{\partial(\mathbf{u} u_x)}{\partial x} = \rho \left(\frac{\partial u_x}{\partial x} \mathbf{u} + u_x \frac{\partial \mathbf{u}}{\partial x} \right), \\ \frac{\partial(\rho \mathbf{u} u_y)}{\partial y} &= \rho \frac{\partial(\mathbf{u} u_y)}{\partial y} = \rho \left(\frac{\partial u_y}{\partial y} \mathbf{u} + u_y \frac{\partial \mathbf{u}}{\partial y} \right), \\ \frac{\partial(\rho \mathbf{u} u_z)}{\partial z} &= \rho \frac{\partial(\mathbf{u} u_z)}{\partial z} = \rho \left(\frac{\partial u_z}{\partial z} \mathbf{u} + u_z \frac{\partial \mathbf{u}}{\partial z} \right). \end{aligned}$$

Substitute the revised expressions into Equation 3.8:

$$\left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) \mathbf{u} + \rho \left(\frac{\partial \mathbf{u}}{\partial t} + u_x \frac{\partial \mathbf{u}}{\partial x} + u_y \frac{\partial \mathbf{u}}{\partial y} + u_z \frac{\partial \mathbf{u}}{\partial z} \right) = -\nabla p + \mu \nabla^2 \mathbf{u} + \rho \mathbf{f}, \quad (3.9)$$

or in compact form,

$$\rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla p + \mu \nabla^2 \mathbf{u} + \rho \mathbf{f}. \quad (3.10)$$

which is the final expression of the N-S equation that we are all familiar with.